

Speak Less, Hear Enough: On Dynamic Announcement Intervals in Wireless On-demand Networks

L. Baumgärtner, P. Graubner, <u>J. Höchst</u>, A. Klein, B. Freisleben WONS2017 — February 21 - 24, 2017

https://www.uni-marburg.de/fb12/arbeitsgruppen/verteilte_systeme



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Announcement protocols

Network protocols relying on broadcasting announcements:

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Announcement protocols

Network protocols relying on broadcasting announcements:

- Service Discovery: Bonjour / ZeroConf
- Routing Protocols: RIP, OLSR
- Delay-tolerant Networking (DTN): Forban, Serval



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Bandwidth in wireless networks (802.11, Bluetooth) is limited.



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- **Epidemic routing** to as many neighbors as possible.



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- **Epidemic routing** to as many neighbors as possible.
- Static nodes (*islands*):
 - people trapped in houses, emergency camps, etc.
- Moving nodes (carrier-pigeons):
 - by bike, car, foot, etc.

Introduction



Delay-tolerant data exchange



Figure: Drive-by store-and-forward data exchange.

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Introduction



Delay-tolerant data exchange



Figure: Drive-by window of opportunity example.

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DTN drawbacks

- r = 40m: WiFi radius
- d = 10m: Node-to-street distance
- v = 50 km/h: drive-by speed
- ightarrow under 6 seconds for node discovery and exchange of data.

High announcement rates: **more** power consumed, **low** announcement rates: data exchange **time reduced**.



Basic idea

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Regular static announcements: Announce myself to the other nodes within a **fixed time delay**.

Dynamic announcements: **Adapt** announcement rate **dynamically**, based on multiple properties.



Interface for announcement computation

Access to a few general purpose variables:



Interface for announcement computation

Access to a few general purpose variables:

current announcement delay



Interface for announcement computation

Access to a few general purpose variables:

- current announcement delay
- global announcement count



Interface for announcement computation

Access to a few general purpose variables:

- current announcement delay
- global announcement count
- current number of unique peers



1. Static: fixed 2s announcement interval



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- 2. Random: random announcement interval



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- 3. RandomSweet: new random interval, if global count is bad



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- 6. MaxFirst: defensive set to low rate and raise step-by-step



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- 7. *MinFirst*: **aggressive** set to high rate and lower step-by-step
- 8. Unsteady: delay derived directly from the number of nodes





Observation delay:

compute announcement interval afterwards



- compute announcement interval afterwards
- announce at least once per observation delay



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- globally defined for all nodes



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- the higher, the longer the network needs to adapt to new situations



- compute announcement interval afterwards
- announce at least once per observation delay
- globally defined for all nodes
- the higher, the longer the network needs to adapt to new situations
- 20 seconds used in this paper



Quality measuring properties

Main goal: 1 second global announcement delay

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Quality measuring properties

Main goal: 1 second global announcement delay

- Global Anouncement Rate: announcements per second
- (Global Announcement Gaps: time between two announcements)
- Adaptation Rate: time needed to adapt to the new rate
Implementation



Example Application: Mesher

Implementation



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simple local chat, written in Google's Go



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- simple local chat, written in Google's Go
- 642 bytes broadcast packets for neighbor discovery and database status updates



Example Application: Mesher

- simple local chat, written in Google's Go
- 642 bytes broadcast packets for neighbor discovery and database status updates
- JavaScript-based API for dynamic announcement computation



Evaluation setup: network emulation



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Centralized network: all nodes connected centrally



¹⁴ Evaluation setup: network emulation

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- Growing network: nodes added periodically



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¹⁴ Evaluation setup: network emulation

- Centralized network: all nodes connected centrally
- Growing network: nodes added periodically
- *Merging network*: merge of two equally sized networks
- Splitting network: split into two equally sized networks





Raspberry Pi 3 Model B single-board computers



- Raspberry Pi 3 Model B single-board computers
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- 8 network participants



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- 1 system under test (SUT)



¹⁵ Evaluation setup: physical testbed

- Raspberry Pi 3 Model B single-board computers
- Vendor-provided Debian-based Raspbian OS
- 8 network participants
- 1 system under test (SUT)
- Data-logging at 5 Hz using an Odroid Smart Power



Test configurations

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Test configurations

Eight announcement strategies



Test configurations

- Eight announcement strategies
- Number of nodes: 2, 5, 10, 25, 50, 100, 200



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- Number of nodes: 2, 5, 10, 25, 50, 100, 200
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- two dynamic network configurations: Split and Merge



Test configurations

- Eight announcement strategies
- Number of nodes: 2, 5, 10, 25, 50, 100, 200
- batch node start, delayed node start
- two dynamic network configurations: Split and Merge
- total of 224 independent experiments



Announcements in a 25 node static network (1)



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¹⁸ Announcements in a 25 node static network (2)

All non-random strategies reach the goal of a **less saturated network** and also approach **the same minimum**.

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Adaptation rate

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²⁰ Adaptation rate

 Unsteady and MaxFirst show very high adaptation rates, since the announcement delay is set after the first observation delay.



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Adaptation rate

- Unsteady and MaxFirst show very high adaptation rates, since the announcement delay is set after the first observation delay.
- MaxFirst achieves a high rate in larger islands, while MinFirst achieves a higher adaptation rate in smaller islands.
- Adaptation rates of *Step*-based strategies depend on the number of nodes.



Adaptation rate: 10 nodes split



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²² Adaptation rate: 100 nodes delayed



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# Nodes Name	2	5	10	25	50
Static	291	732	1460	3658	7296
Random	34.4%	47.0%	37.0%	37.9%	37.3%
RandSweet	58.1%	41.7%	29.0%	35.6%	37.7%
Step	101.7%	45.4%	35.2%	33.2%	33.4%
StepRand	99.7%	42.5%	32.5%	30.1%	30.2%
MaxFirst	99.0%	21.2%	17.1%	17.0%	17.1%
MinFirst	84.9%	44.3%	34.7%	33.3%	33.5%
Unsteady	188.7%	56.8%	32.5%	17.7%	17.1%

Table: Bandwidth Comparison



²⁴ Bandwidth savings

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• *Step*, *StepRand* and *MinFirst*: **bandwidth savings** > 60%.



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- Unsteady and MaxFirst: bandwidth savings > 80%
 → quick adaptation to the given situations.



²⁴ Bandwidth savings

- *Step*, *StepRand* and *MinFirst*: **bandwidth savings** > 60%.
- Unsteady and MaxFirst: bandwidth savings > 80%
 → quick adaptation to the given situations.
- Unsteady: 188.7% of Static in a two nodes network.
 → low announcement delays in small networks achievable.



Energy consumption: setup

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Energy consumption: setup

• 8 regular nodes, 1 system under test



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- ad-hoc (1.35 W idle consumption) and managed mode (1.45 W)



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- added Static05 and Static01, with 2 / 10 announces per second



Energy consumption: setup

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- ad-hoc (1.35 W idle consumption) and managed mode (1.45 W)
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$$E:=\int_{0}^{300} P_{measured}(t)\,\mathrm{d}t-300*P_{idle}$$



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Name	# Ann.	E (mWh)	rel. Ann.	rel. E	ratio
Static	1323	1.99	1.00	1.00	1.00
Static05	5404	11.97	4.08	6,00	1.47
Static01	29342	32.52	22.18	16.31	0.74
MaxFirst	256	1.17	0.19	0.59	3.04
MinFirst	473	1.26	0.36	0.63	3.04
Random	434	1.34	0.33	0.67	2.04
RandomSweet	342	0.73	0.26	0.37	1.42
Step	495	1.20	0.37	0.60	1.61
StepRand	460	1.12	0.35	0.56	1.61
Unsteady	514	1.38	0.39	0.69	1.78

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Energy consumption: overall results

- General trend proven: less announcements \rightarrow less power consumed



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- correlation coefficient r = 0.985



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- correlation coefficient r = 0.985
- Side-effects due to programming language, OS, ...
- though relatively small, announcements effect battery lifetimes



Conclusion

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²⁸ Conclusion

• Eight different announcement strategies compared



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- reduction by 80% compared to a static strategy, while reaching the goal of a fast island discovery.



- Eight different announcement strategies compared
- reduction by 80% compared to a static strategy, while reaching the goal of a fast island discovery.
- Energy impact: announcements effect battery lifetimes and are worth to be reduced.

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Future Work

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• More realistic WiFi emulation, eg. Island center vs. edge nodes



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- Design algorithms based on additional information



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- Evaluate on real world applications eg. Serval



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- Design algorithms based on additional information
- Evaluate on real world applications eg. Serval
- Make software use dynamic announcements.



Thanks for your Attention!

Are there any questions?

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